

I Unit D.C. Generator. F & E III sem

Q. No. 6
2m

~~Machine~~
Explain the principle of DC generator works.

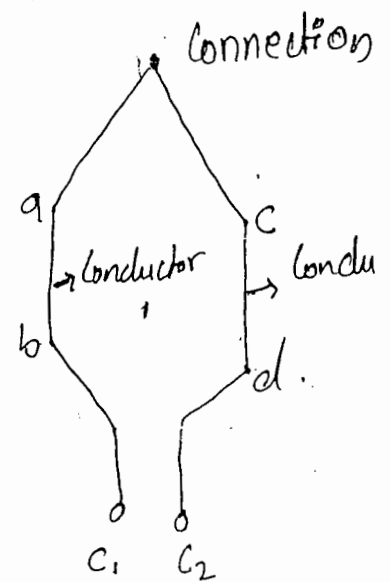
The DC generator works on the principle of Faraday's Law of electromagnetic induction.

Faraday's Law states that whenever a conductor cuts the magnetic lines of force an EMF is induced in the conductor. This EMF causes to flow if conductor circuit is closed.

The relative motion can be achieved by rotating conductor w.r.t flux. This principle is nothing but dynamically EMF induced.

Simple Loop Generator :-

It consists of permanent magnet with two poles. The coil is made up of conducting material like copper or aluminium. The coil is made up of two conductors a-b and c-d such conductors are connected at one end to form a coil as

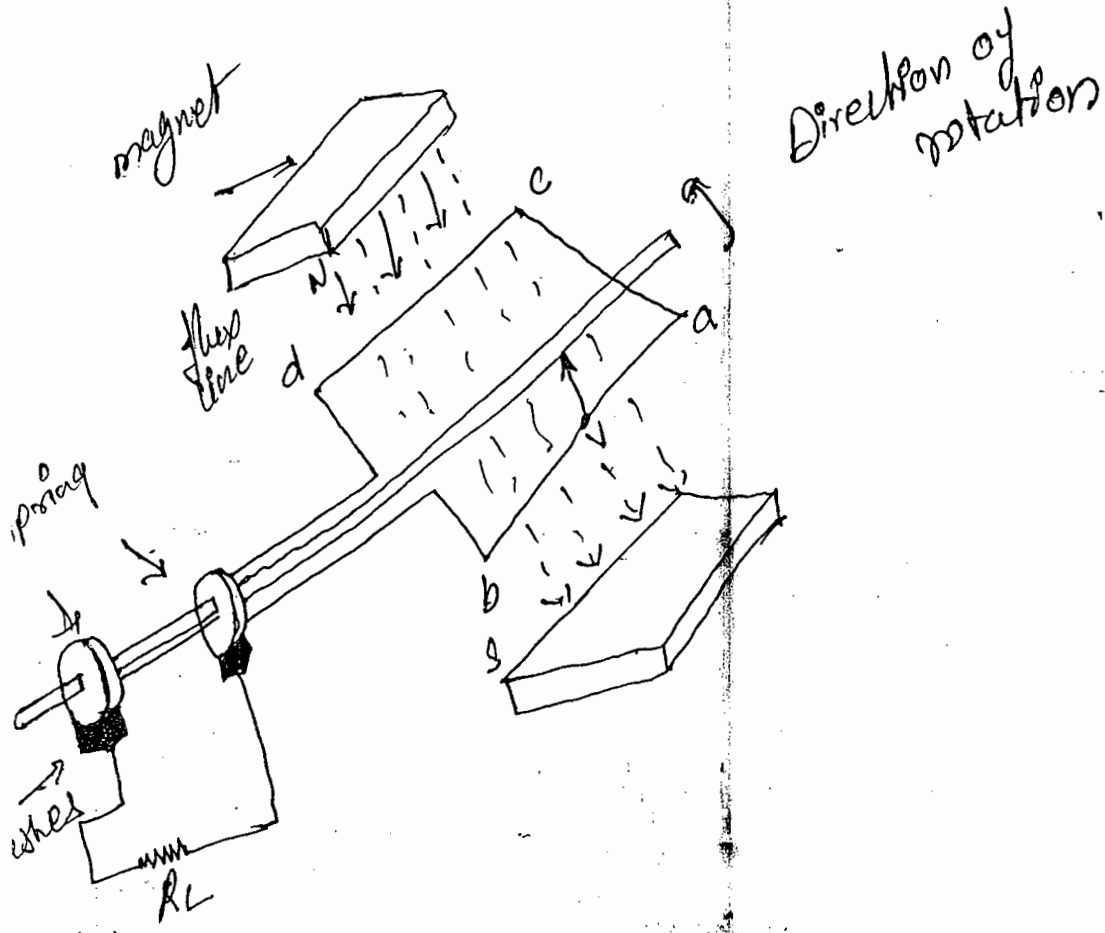


shown in figure. The remaining two ends are connected to ring mounted on shaft called slip rings C1 & C2

Slip rings rotate along with armature of a

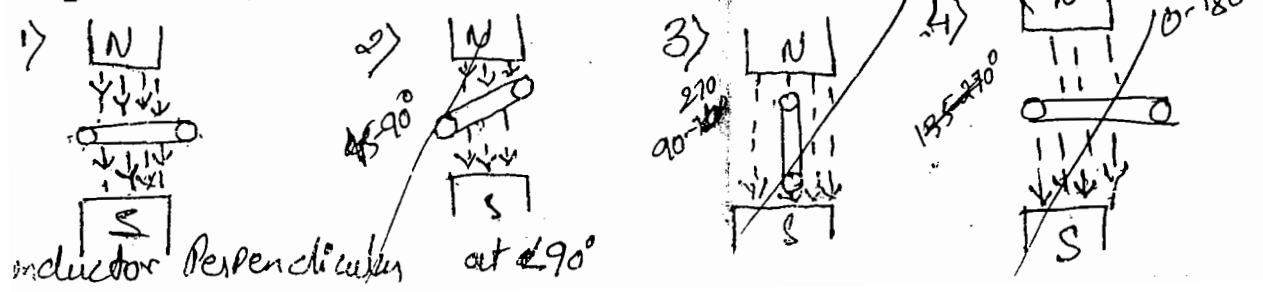
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on one slip rings. The brushes K and C are stationary. The slip ring and brush is required to collect the EMF induced in the rotating coil. The overall figure is as shown below

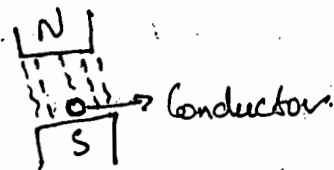
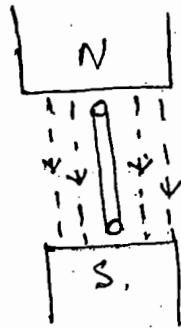


If coil is rotated in an anticlockwise direction while rotating the conductor cuts the magnetic lines of force. Hence EMF is induced in the conductor. This EMF drive a current through Resistance.

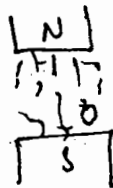
Sin wave



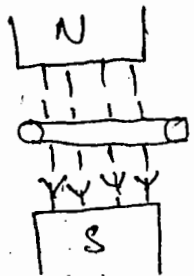
1) The conductor is placed at 0° as shown in figure. The conductor is parallel to flux. Hence conductor ~~does not~~ cut's the flux, ~~no~~ EMF induced in the conductor.



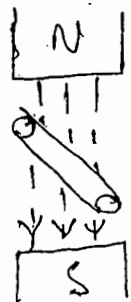
2) The conductor is placed as shown in fig. The conductor cuts the magnetic lines of force hence EMF induced in the conductor.



3) The conductor is placed as shown in figure. The conductor is parallel to flux hence maximum flux cuts by the conductor and EMF induced in the conductor.



4) The conductor is placed as shown in figure the conductor rotates at an angle. Hence the flux links with the conductor and EMF is induced in the conductor.



Construction of DC machine :-

1) Yoke :- * Function.

- 1) It serves as outermost cover of DC machine
- 2) It protect harmful atmospheric element like moisture, dust and various gases. etc
- 3) It provide mechanical support to the poles.

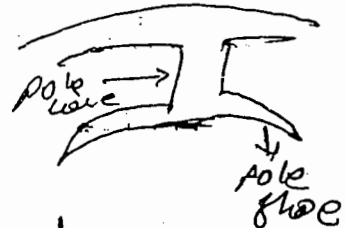
Choice of materials

- 1) To provide low reluctance path.
- 2) It should made up of magnetic material
- 3) It should made up of cast iron

2) Poles :- function

1) Each pole divided into two parts.

- a) pole core
- b) pole shoe.



Functions

- 1) pole core carries a field winding to produce flux.
- 2) pole shoe enlarges the area of armature core to come across the flux, which is necessary to produce larger flux.

Choice of material.

- 1) It is made up of cast iron or cast steel
- 2) It should carry low reluctance path.

3) Field winding :- The field winding is wound on the pole core.

- Function :-
- 1) It is used to carry current which produces necessary flux.
 - 2) It helps to produce magnetic field.

Choice of material

- 1) It should be made up of conducting material. Such as copper etc.
- 2) It should take any shape and bend easily.

4) Armature - It is divided into two parts - namely
Armature core 2) Armature winding.

1) Armature core :- Armature core is cylindrical shape mounted on shaft.

Slots :-

- 1) It consists of slots in which windings are placed.
- 2) It provides a low reluctance path to magnetic field.

Choice of material :-

- 1) To provide low reluctance path.
- 2) Material should be made up of cast iron or cast steel.
- 3) Core should be laminated.

armature winding :- The interconnection of the armature conductors placed in the slots.

Function :- 1) Generation of emf in case of generator.

2) To carry current supplied in case of DC motor.

Choice of material :-

1) It should carry current depend upon load.

2) It should be conducting material.

5) Commutator :- ^{Commutator} ~~It~~ produces AC. Hence in case of DC generator rectification is required. which is possible by use of commutator.

Function :- 1) It should collect the current from armature conductors.

2) Convert AC to DC supply internally.

Choice of material :-

1) It should be made up of copper segment.

2) These segments are insulated from each other.

3) Mica sheets are used to separate segments.

6) Brushes :-

function :- To collect current from commutator and make it available to stationary.

It supplies current in case of motor.

Choice of material :-

- 1) brushes are made up of carbon or graphite.
- 2) brushes are rectangular in shape.
- 3) to collect current from commutator.

6) Choi

- 7) Bearing :-
- > Ball bearing are generally used for more reliable.
 - > for heavy duty machines roller bearing's are preferred.

Properties of materials used for D.C machine

- 1) winding resistivity of a material used for winding is low.
- 2) The resistive temperature Co-efficient is low.
- 3) The material should have high magnetic permeability.
- 4) Hysteresis loop is narrow, and having small area.

- 5) The magnetic material have high saturation limits.
- 6) low reluctance
- 7) The resistivity of the material used for Yoke and cores is high.

Properties of Slot Insulation materials

- 1) very high Insulation resistance
- 2) High dielectric strength
- 3) Low dielectric loss
- 4) No attraction of moisture
- 5) Good heat conductivity
- 6) High melting point.
- 7) Sufficient mechanical strength to withstand bending & vibration.

Types of Armature Winding :-

A number of armature conductors are connected in specific manner as per requirements.

⊕ There are two types Armature winding.

a) Lap winding

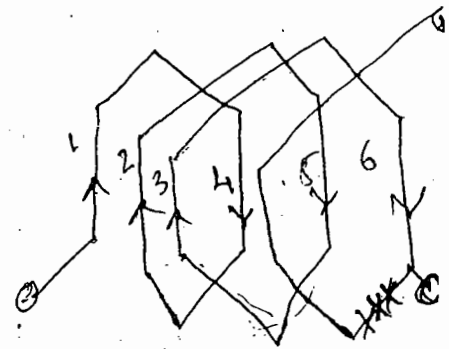
b) Wave winding.

Lap
wave
Simplex
duplex

a) Lap winding.

In this case if connection is started from conductor in slot 1 then connection overlap each other as winding proceeds till starting point reached again.

Developed view of part of the armature winding is as shown in figure



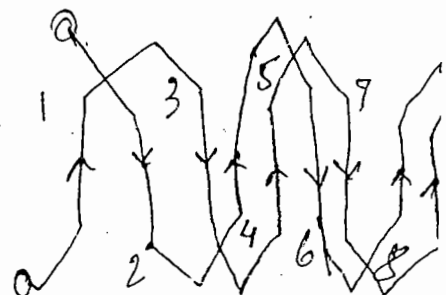
The total number of conductors get divided into "P" number of parallel paths

where

$P = \text{number of poles in machine}$

Wave Winding :-

In this type of connection, winding always travels ahead avoiding overlapping



④ It travels like a progressive wave hence it is called wave winding

⑤ The total number of conductors get divided into two number of parallel path always, irrespective of number of poles (P) of the machine.

⑥ so $A = P$ for lap connection
& $A = 2$ for wave connection

Rules for the winding

A 2 wave

1) Both winding are full pitch. both back pitch & front pitch are each almost equal to the pole pitch.

Due to this there is increase in emf induced around coil.

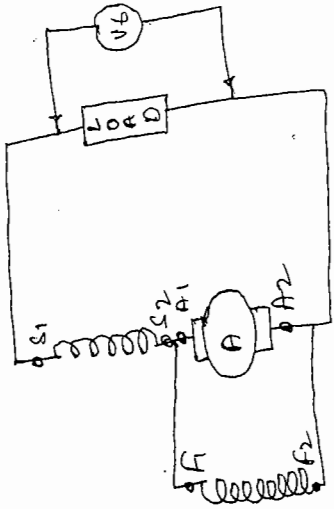
2) Both back pitch and front pitch must be odd number which helps to design the winding easily

3) The front ends of the conductors are joined to the commutator segments in pairs hence number of commutator segments is always equal to the number of slots

4) The entire winding must be closed path.

5) The average pitch for the lap winding is $\frac{Z}{P}$ while that for the wave winding is $\frac{Z \pm 2}{P}$

Shunt Compound generator :-



is this type of generator The field winding is connected across armature winding alone.

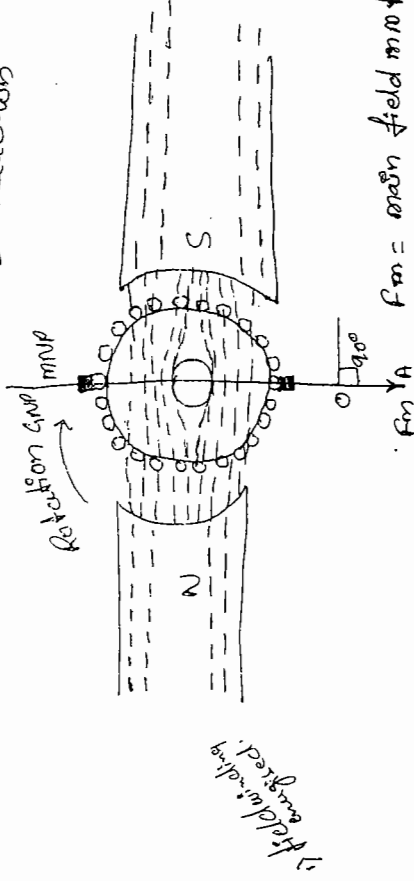
This type of generator is called short

shunt compound generator.

Performance of DC Generator

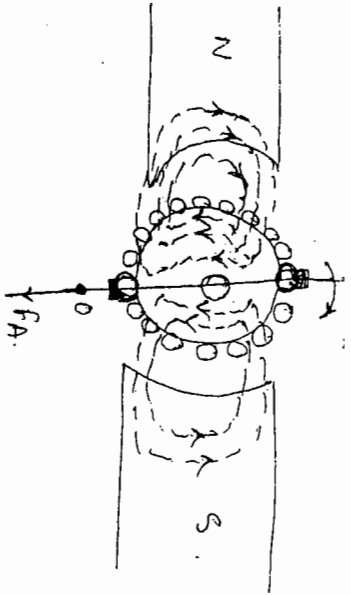
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Armature Reaction :- The effect of magnetic field setup by the armature current on distribution of the flux under main poles. is called as Armature Reaction

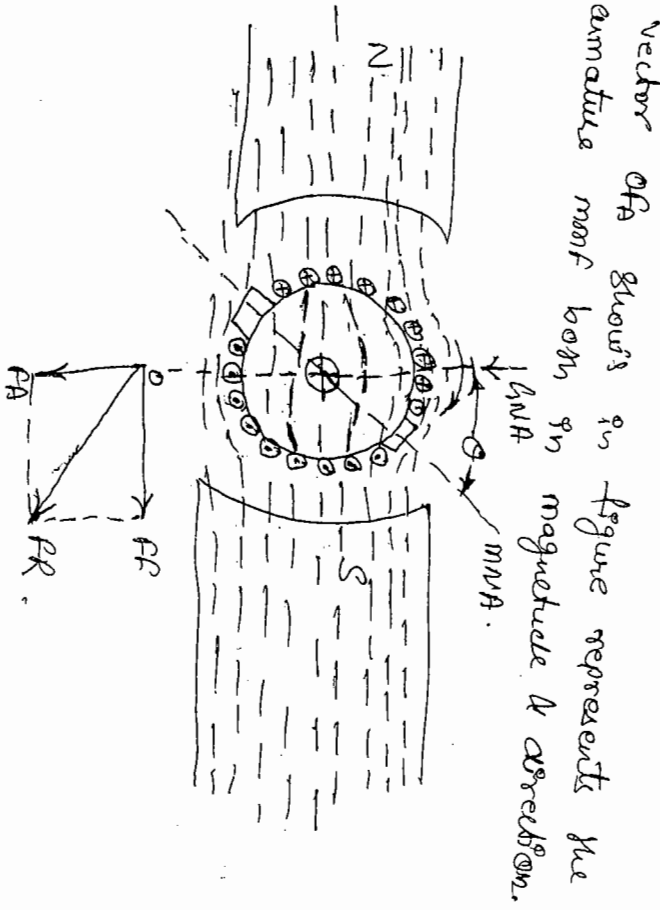


Consider an armature rotating in clockwise direction. when field winding energised, the field flux is distributed as shown in figure. Assume the generator is on no load.

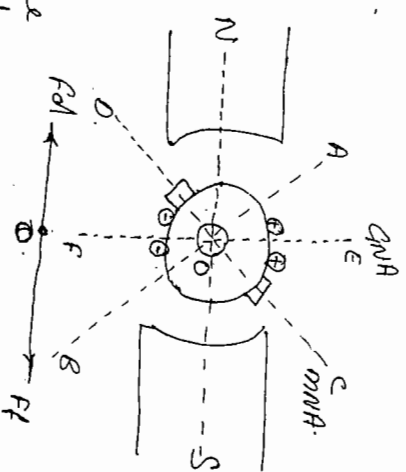
The brushes will make contact with conductors lying on magnetic neutral axis (MNA) which coincide with Geometric neutral plane (GNP). No EMF induced in armature conductor is known as MNA.



Now we consider that field coils are unexcited. ~~whereas~~ armature conductors are carrying current. Under this case field set up by armature conductors as shown in figure. The direction of current in armature conductor is determine by Fleming's right rule. The current carrying armature conductor try to magnetise the armature core along with brush axis.



- * Due to interaction of two fluxes the wave distribution flux is changed as shown in fig.
 - * The pole tip which met first during rotation by armature conductors is known as leading pole and other is known as trailing pole tip.
 - * The resultant field F_R is perpendicular to new MNA . The new MNA is shifted through an angle α so that brushes are also shifted.
 - * Due to brush shift the armature conductors as and armature current is redistributed as shown in figure.
- (Q2). Demagnetising Effect.
- * In the figure it is clear that the new MNA is shifted the new position of MNA is at angle α from MNA due to armature reaction.
 - * The armature are carrying the current in such direction ~~that~~ as to send flux in armature from right to left.
 - * Thus these conductors are in direct opposition to main field and is called as demagnetising effect.

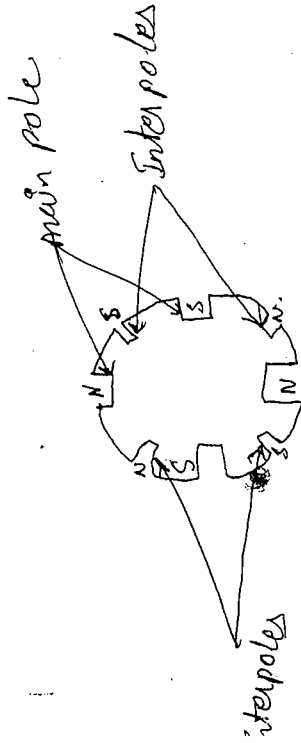


ving Brush Shift :-

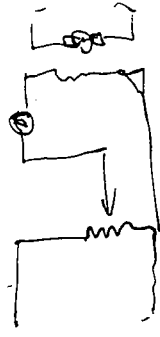
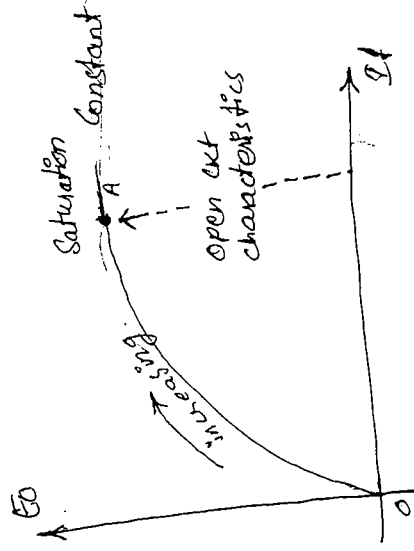
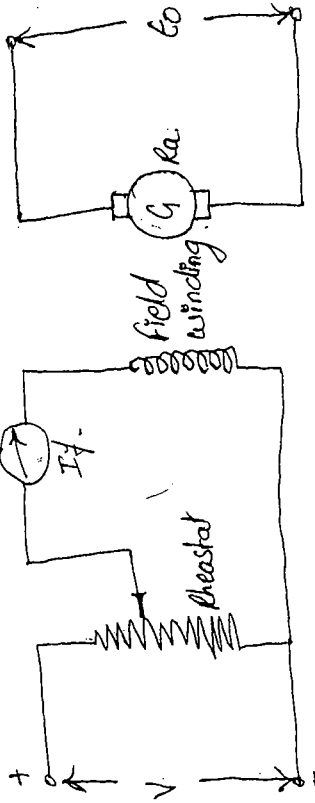
If the brushes are shifted forward or backward depends on generator or motor. The short circuit coil will come under influence of main pole of opposite polarity.

Interpoles :-

By using small poles fixed to the yoke and placed in between the main poles, along with CMA. these poles are called as interpoles. This interpoles are used to ~~netto~~ neutralize reactance voltage.



Characteristics of Separately Excited Dc Generator.



* The above figure shows the characteristics of Separately excited Dc generator.

* The rheostat is used to control the field current and flux.

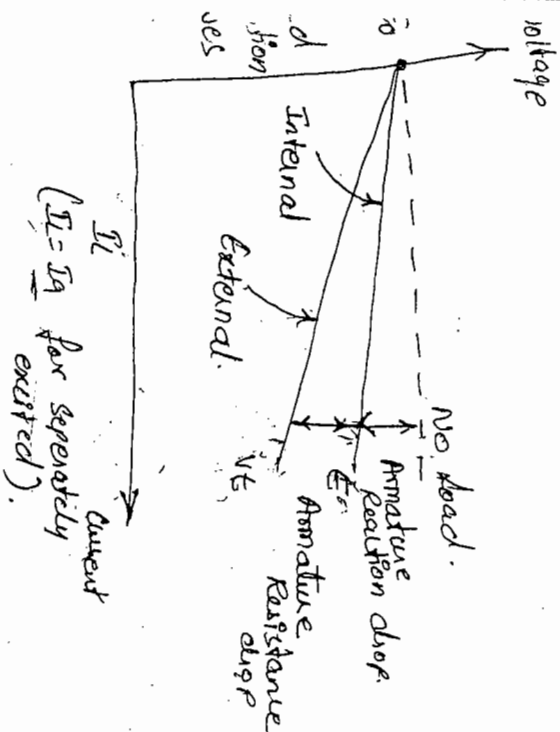
* I_f is varied from zero and measured by ammeter connected. $[E_0 = \phi P N Z / 60 \times A.]$

* As I_f varied, the flux changes and EMF induced across armature.

No load is connected to machine hence characteristics is also called as No. load characteristics.

If I_f increases, flux Φ increases and EMF E_o increases. After a point A saturation occurs when Φ becomes constant and hence E_o saturates.

Internal & External characteristics of Separately excited DC generator.



* Let E_o be the no load rated voltage with drop to E due to armature reaction on and further drops due to V_t due to armature resistance drop $I_a R_a$ on load.

$$E_o = V_t + I_a R_a$$

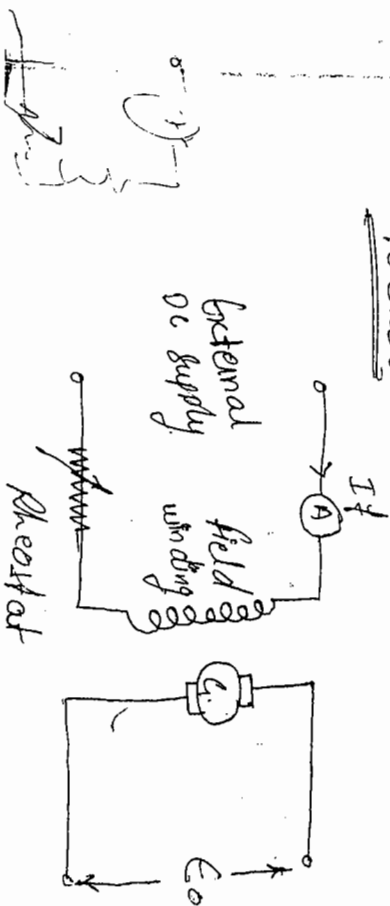
* The graph of V_t against load current I_a is called external characteristics.

* The graph of E against load current I_a is called internal characteristics.

* The figure shows the separately excited DC generator characteristics.

* The EMF induced is totally dependent on (ΦI_f) flux hence to control over field current the field regulator is necessary.

Open Circuit Characteristics of DC Shunt Generator



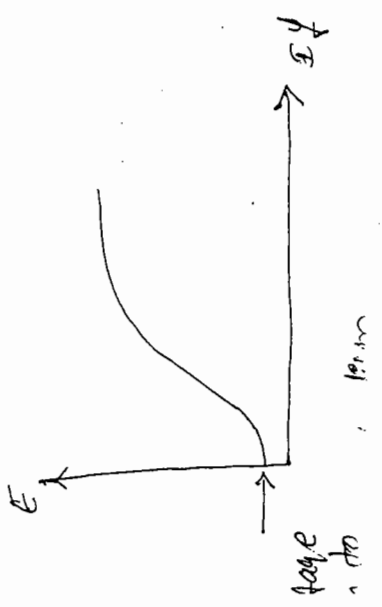
The open ckt characteristics is similar to separately excited DC generator.

The machine is driven at constant speed. The field current (I_f) is varied by using Rheostat and measured by ammeter.

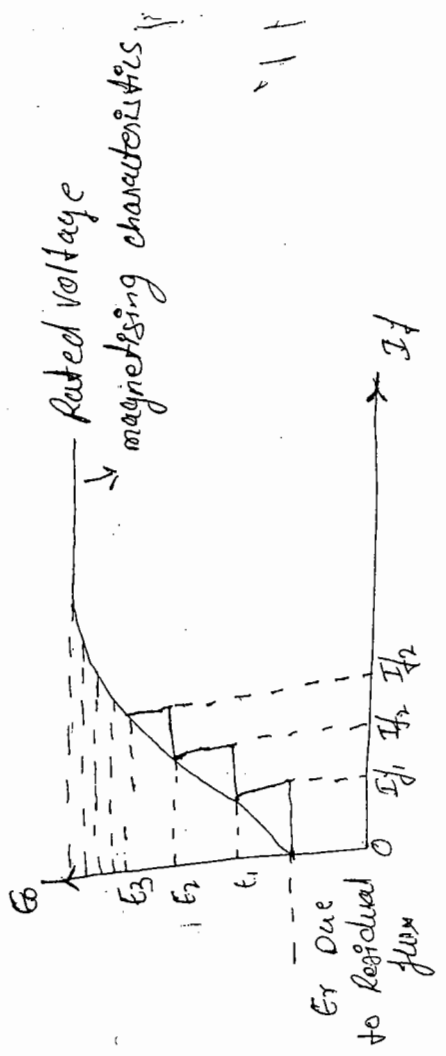
The open ckt EMF generated is measured by Voltmeter.

The graph against E_0 vs I_f is called OCC (open circuit characteristics).

Due to residual magnetism there is small voltage present $I_f = 0$ Amp Hence graph does not pass through origin.



Voltage Building in Self Excited Shunt Generator



- ① For every self excited generator there must be existence of Residual magnetism.
- ② when armature rotates, conductor cut this small residual flux to produce EMF.
- ③ Thus field current produce more current which is greater than residual flux hence more EMF is induced.
- ④ This process continues till rated voltage gets build up as shown in figure.

Conditions to Build up Voltage in Shunt Generator :-

- Residual magnetism must be present
- The field connection should be proper
- Inter change of connection may cancel the residual magnetism.
- The field resistance must be less than the critical Resistance value.
- The generator must be driven in proper direction by prime mover.

External Characteristics of DC Shunt Generator

- 1) The graph of V_t (Terminal Voltage) against field current (I_f) is called external characteristics.
- 2) In DC generator there are three reasons to reduce V_t as I_L increases.



1) As I_L increases, armature current I_a increases due to R_a to V_t voltage drops by $I_a R_a$.

2) As I_a increases, armature reaction increases which weakens the main flux hence E_m induced decreases.

3) As V_t decreases by above two reasons (I_f) decreases, hence flux decreases which decreases in the induced E_m .